



Numerical benchmarking of fluid-structure interaction between elastic object and laminar incompressible flow

DFG-Forschergruppe 493 Fluid-Struktur-Wechselwirkung: Modellierung, Simulation, Optimierung

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Key questions

- ☞ Accurate and robust description of the **interaction mechanisms** w.r.t. highly dynamical and nonlinear behaviour and significant geometry changes? That includes:
 - Quality of different discretization techniques (FEM, FV, FD, LBM, resp., beam, shell, volume elements) for FSI?
 - Robustness and numerical efficiency of the integrated solver components?
- ☞ **Evaluation of partitioned approaches vs. monolithic schemes?**

1st step: *Identification of appropriate FSI setting for numerical benchmarking*

2nd step: *FSI benchmark setting due to experimental studies*





Requirements for numerical FSI benchmarking

☞ mainly based on the successful DFG *flow around cylinder* benchmark

☞ *realistic materials*

- **incompressible Newtonian fluid**, laminar flow regime
- **elastic solid**, large deformations

☞ *comparative evaluation*

- setup with periodical oscillations
- non-graphically based quantities

☞ *computable configurations*

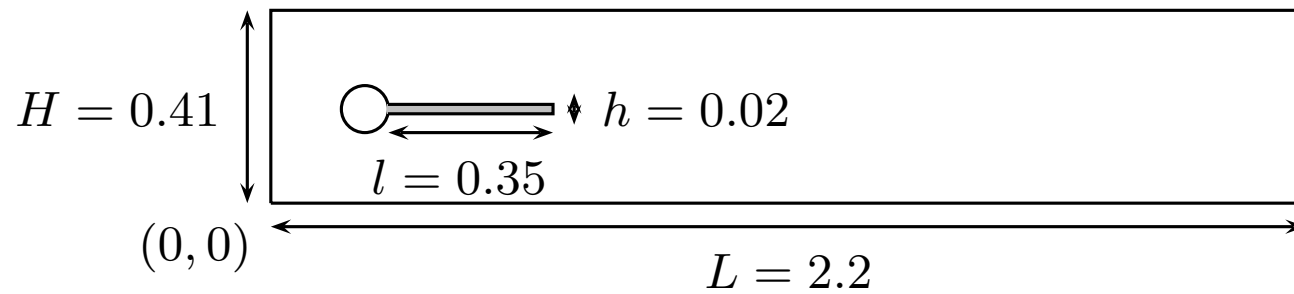
- laminar flow
- reasonable aspect ratios
- simple geometry (2D)



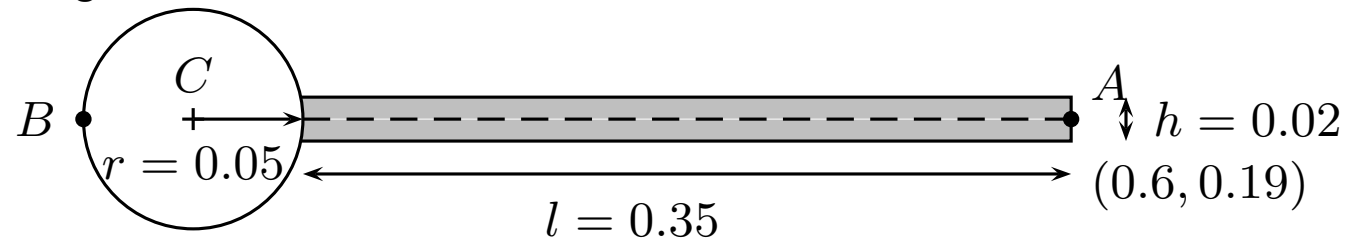


Computational domain

👉 domain dimensions



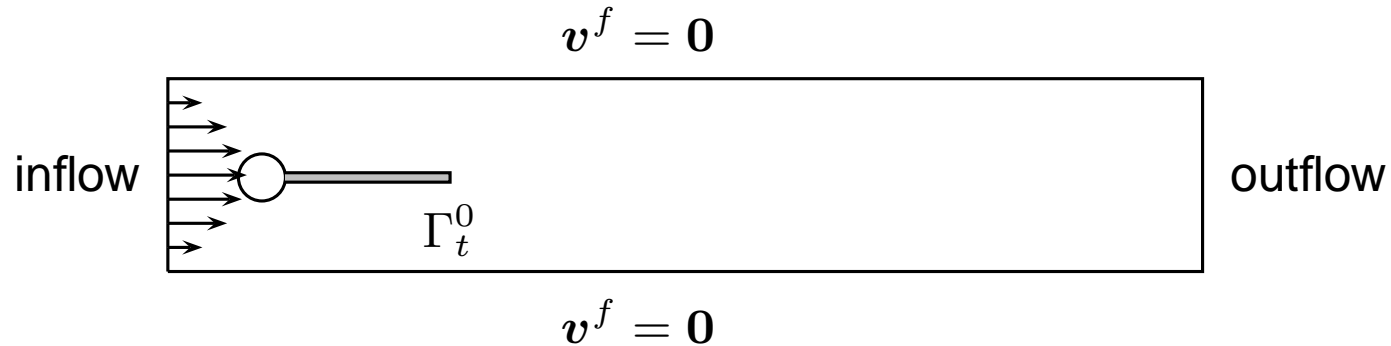
👉 detail of the submerged structure



👉 $A(t = 0) = (0.6, 0.2)$, $B = (0.15, 0.2)$, $C = (0.2, 0.2)$



Boundary and initial conditions



inflow parabolic velocity profile is prescribed at the left end of the channel

outflow condition can be chosen by the user, assuming zero reference pressure (*stress free or do nothing*)

interface condition on Γ_t^0 is $v^f = v^s$ and $\sigma^f n = \sigma^s n$

otherwise the *no-slip* condition is prescribed for the fluid on the other boundary parts. i.e. top and bottom wall and cylinder

initial zero velocity in the fluid and no deformation of the structure + smooth increase of the inflow profile



Fluid and structure properties

☞ **Incompressible** fluid with density ϱ^f

$$\begin{aligned} \varrho^f \frac{\partial \mathbf{v}^f}{\partial t} + \varrho^f (\nabla \mathbf{v}^f) \mathbf{v}^f &= \operatorname{div} \boldsymbol{\sigma}^f && \text{in } \Omega_t^f \\ \operatorname{div} \mathbf{v}^f &= 0 \end{aligned}$$

$$\boldsymbol{\sigma}^f = -p^f \mathbf{I} + \varrho^f \nu^f (\nabla \mathbf{v}^f + \nabla \mathbf{v}^{f\top})$$

☞ Elastic material with density ϱ^s , $\mathbf{F} = \mathbf{I} + \nabla \mathbf{u}^s$, $J = \det \mathbf{F}$: **St. Venant – Kirchhoff** material

$$\varrho^s \frac{\partial^2 \mathbf{u}^s}{\partial t^2} = \operatorname{div}(\boldsymbol{\sigma}^s \mathbf{F}^{-\top}) \quad \text{in } \Omega^s$$

$$\boldsymbol{\sigma}^s = \frac{1}{J} \mathbf{F} (\lambda^s (\operatorname{tr} \mathbf{E}) \mathbf{I} + 2\mu^s \mathbf{E}) \mathbf{F}^\top$$

$$\mathbf{E} = \frac{1}{2} (\mathbf{F}^\top \mathbf{F} - \mathbf{I})$$





Suggested material parameters

solid

- ρ^s density
- ν^s Poisson ratio
- μ^s shear modulus

fluid

- ρ^f density
- ν^f kinematic viscosity

parameter	polybutadiene & glycerine	polypropylene & glycerine
$\rho^s [10^3 \frac{\text{kg}}{\text{m}^3}]$	0.91	1.1
ν^s	0.5	0.42
$\mu^s [10^6 \frac{\text{kg}}{\text{ms}^2}]$	0.53	317
$\rho^f [10^3 \frac{\text{kg}}{\text{m}^3}]$	1.26	1.26
$\nu^f [10^{-3} \frac{\text{m}^2}{\text{s}}]$	1.13	1.13

parameter	FSI1	FSI2	FSI3
$\rho^s [10^3 \frac{\text{kg}}{\text{m}^3}]$	1	1	1
ν^s	0.4	0.4	0.4
$\mu^s [10^6 \frac{\text{kg}}{\text{ms}^2}]$	0.5	0.5	2.0
$\rho^f [10^3 \frac{\text{kg}}{\text{m}^3}]$	1	1	1
$\nu^f [10^{-3} \frac{\text{m}^2}{\text{s}}]$	1	1	1
$\bar{U} [\frac{\text{m}}{\text{s}}]$	0.2	1	2

parameter	FSI1	FSI2	FSI3
$\beta = \frac{\rho^s}{\rho^f}$	1	1	1
ν^s	0.4	0.4	0.4
$Ae = \frac{E^s}{\rho^f \bar{U}^2}$	3.5×10^4	1.4×10^3	1.4×10^3
$Re = \frac{\bar{U}d}{\nu^f}$	20	100	200
\bar{U}	0.2	1	2





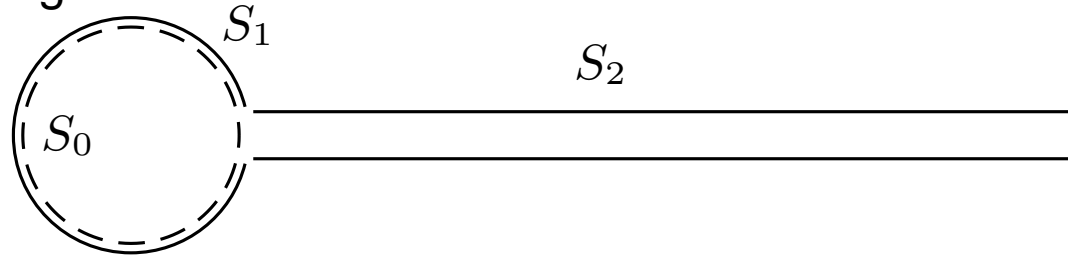
Quantities of interest

☞ the position $A(t) = (x(t), y(t))$ of the end of the structure

☞ pressure difference between the points $A(t)$ and B

$$\Delta p^{AB}(t) = p^B(t) - p^{A(t)}(t)$$

☞ forces exerted by the fluid on the *whole* body, i.e. lift and drag forces acting on the cylinder and the structure together



$$(F_D, F_L) = \int_S \boldsymbol{\sigma} \mathbf{n} dS = \int_{S_1} \boldsymbol{\sigma}^f \mathbf{n} dS + \int_{S_2} \boldsymbol{\sigma}^{f|s} \mathbf{n} dS = \int_{S_0} \boldsymbol{\sigma} \mathbf{n} dS$$

☞ frequency and maximum amplitude

☞ compare results for *one* full period and 3 different levels of spatial discretization h and 3 time step sizes Δt





FSI1: steady, small deformations

parameter	FSI1	FSI2	FSI3
$\rho^s [10^3 \frac{\text{kg}}{\text{m}^3}]$	1	1	1
ν^s	0.4	0.4	0.4
$\mu^s [10^6 \frac{\text{kg}}{\text{ms}^2}]$	0.5	0.5	2.0
$\rho^f [10^3 \frac{\text{kg}}{\text{m}^3}]$	1	1	1
$\nu^f [10^{-3} \frac{\text{m}^2}{\text{s}}]$	1	1	1
$\bar{U} [\frac{\text{m}}{\text{s}}]$	0.2	1	2

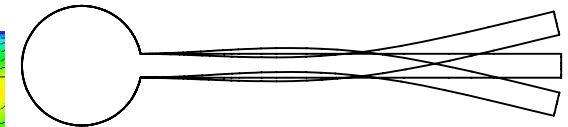
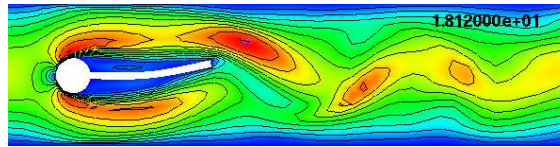
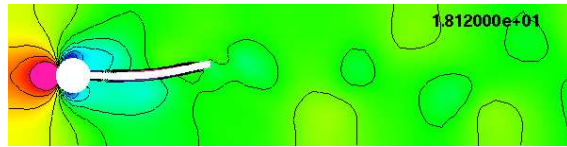
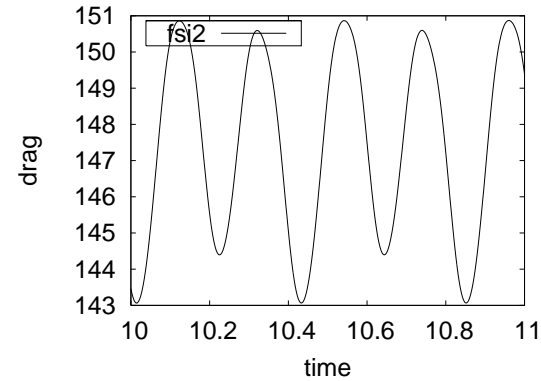
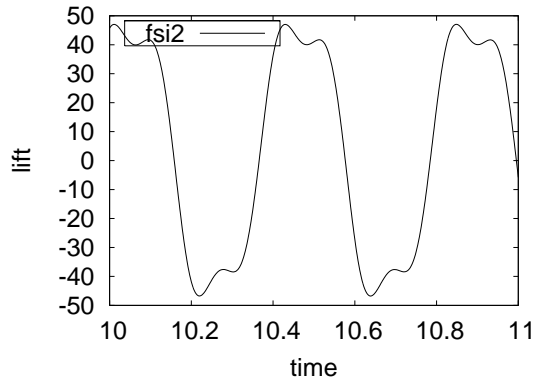
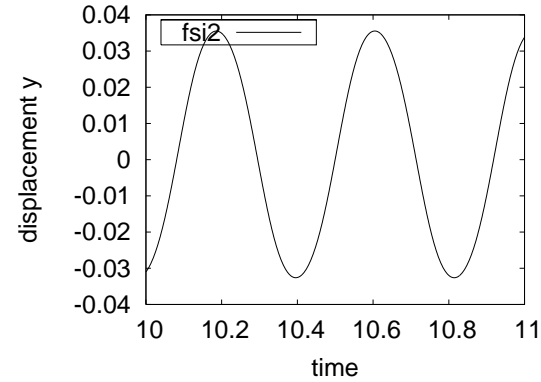
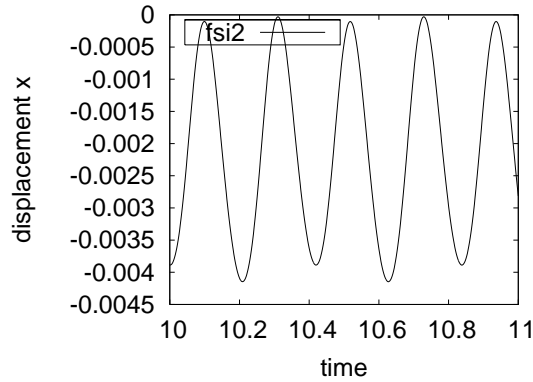
parameter	FSI1	FSI2	FSI3
$\beta = \frac{\rho^s}{\rho^f}$	1	1	1
ν^s	0.4	0.4	0.4
$Ae = \frac{E^s}{\rho^f \bar{U}^2}$	3.5×10^4	1.4×10^3	1.4×10^3
$Re = \frac{\bar{U} d}{\nu^f}$	20	100	200
\bar{U}	0.2	1	2



	ux of A [$\times 10^{-3}$ m]	uy of A [$\times 10^{-3}$ m]	drag	lift
FSI1	0.0227	0.8209	14.295	0.7638



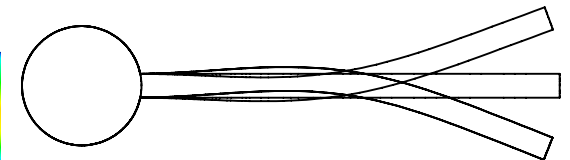
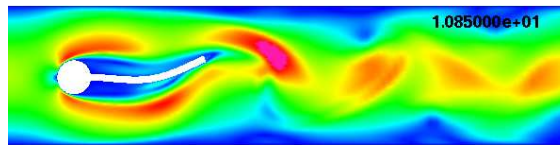
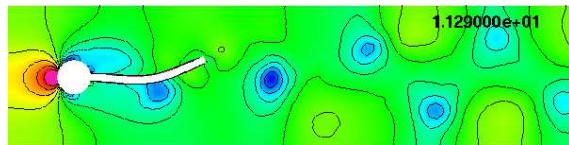
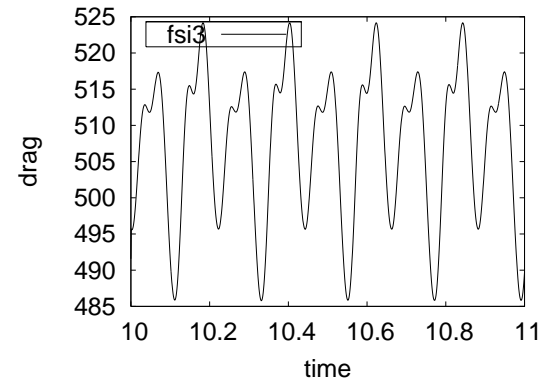
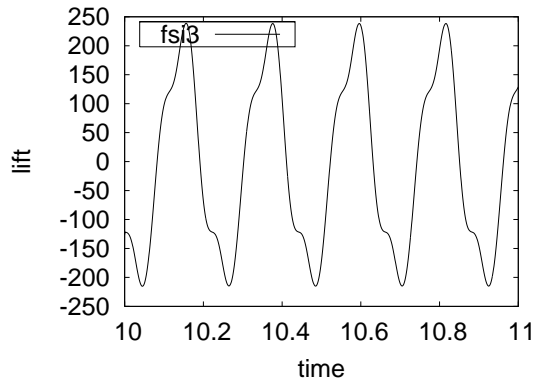
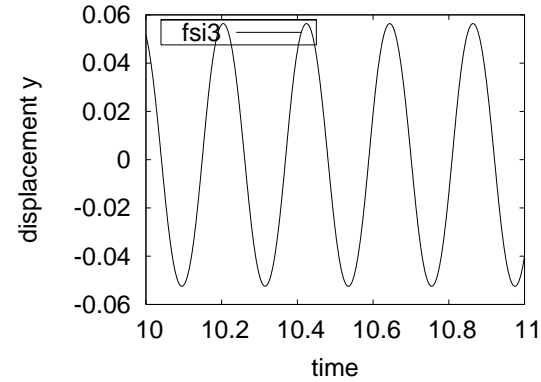
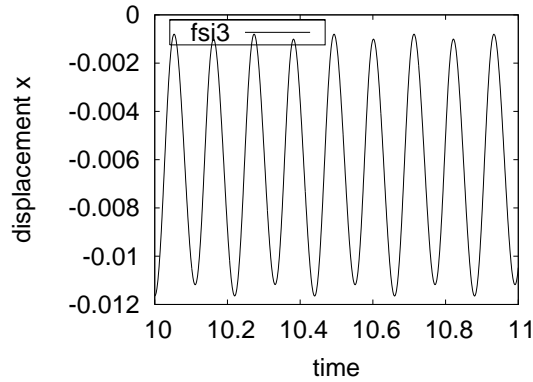
FSI2: large deformations, periodical oscillations



test	ux of A [$\times 10^{-3}$ m]	uy of A [$\times 10^{-3}$ m]	drag	lift
FSI2	$-14.58 \pm 12.44[3.8]$	$1.23 \pm 80.6[2.0]$	$208.83 \pm 73.75[3.8]$	$0.88 \pm 234.2[2.0]$



FSI3: large deformations, complex oscillations



test	ux of A [$\times 10^{-3}$ m]	uy of A [$\times 10^{-3}$ m]	drag	lift
FSI3	$-2.69 \pm 2.53[10.9]$	$1.48 \pm 34.38[5.3]$	$457.3 \pm 22.66[10.9]$	$2.22 \pm 149.78[5.3]$





Current status

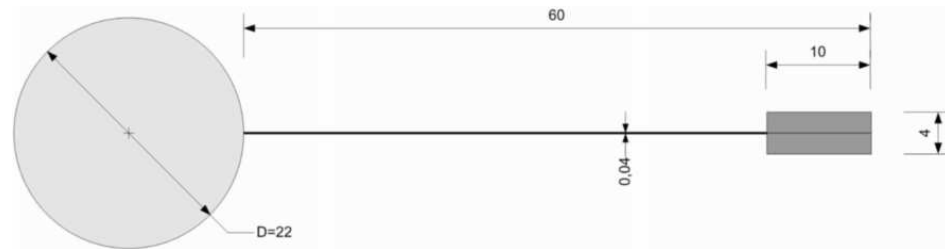
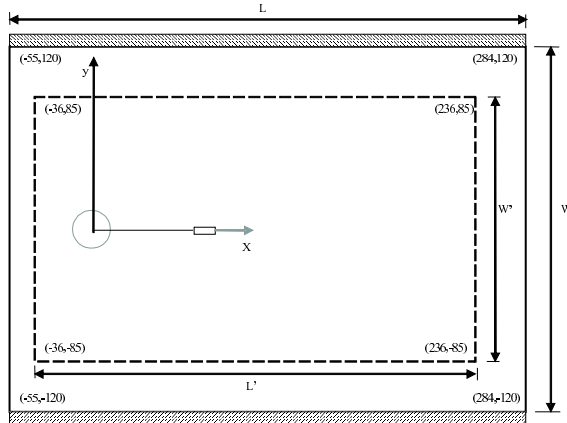
- ☞ Verification of reference values is almost finished (→ new version)
- ☞ Subtests for validating CFD and CSM components are available:
 - CSM1-3: "OK"
 - CFD1: "easy" → $Re = 20$
 - CFD2: (also) "easy" → $Re = 100$
 - CFD3: "non-trivial" → $Re = 200$
- ☞ FSI settings with desired properties:
 - FSI1: "simple" → for validation only
 - FSI3: "hard" → due to CFD3
 - FSI2: fully oscillating while CFD2 (\approx same Re number!) is steady
⇒ **Excellent check for interaction mechanisms**
- ☞ Evaluation and comparison of mathematical and algorithmic components - *everybody is invited to participate.*



Benchmarking of experimental data



Flustruc experiment, Erlangen, <http://www.lstm.uni-erlangen.de/flustruc/>



geometry parameters		value [mm]
channel length	L	338.0
channel width	W	240.0
cylinder center position	C	(0.0, 0.0)
cylinder radius	r	11.0
elastic structure length	l	50
elastic structure thickness	w	0.04
rear mass length	w'	10.0
rear mass thickness	h'	4.0
reference point (at $t = 0$)	A	(71.0, 0.0)
reference point	B	(11.0, 0.0)

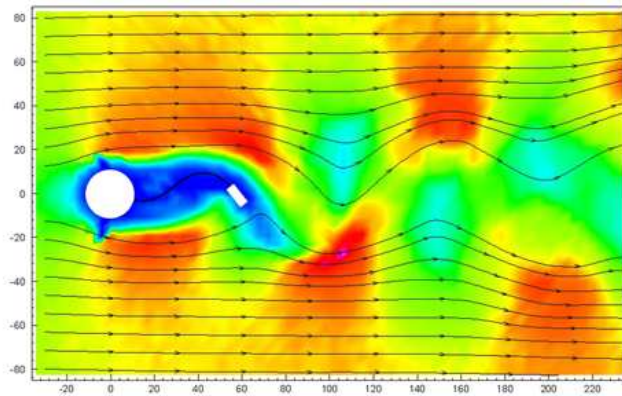
fluid parameters		
density of the fluid	$\rho^f [kg/mm^3]$	$1.05[10^{-6}]$
kinematic viscosity	$\mu^f [mm^2/s]$	164.0
solid parameters		
density of the beam (steel)	$\rho^s [kg/mm^3]$	$7.85[(10)^{-6}]$
density of the rear mass	$\rho^s [kg/mm^3]$	$7.8[(10)^{-6}]$
shear modulus	$[kg.mm.s^2]$	$7.58[(10)^{13}]$
Poisson ratio	ν^p	0.3



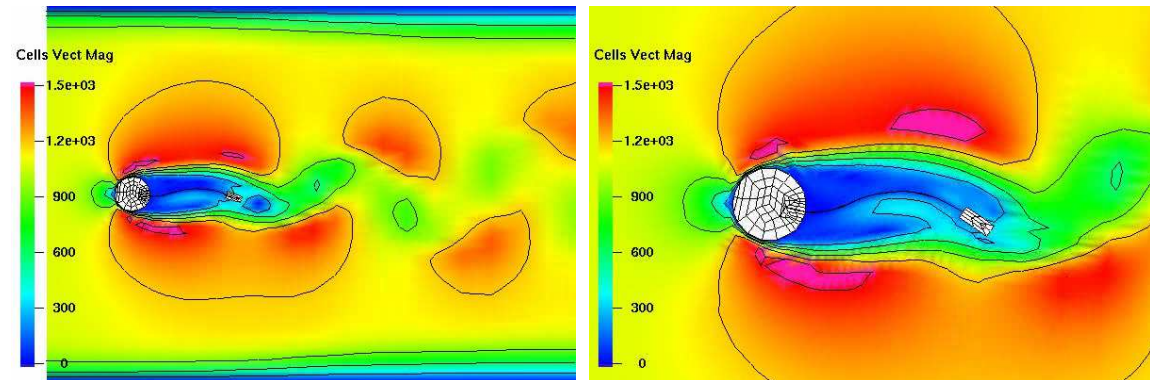
Benchmarking of experimental data



- + laminar flow
- + “2D” flow and deformation
- rotational degree of freedom
- large aspect ratio (thin structure), corners



Flustruc experiment, Erlangen



computation

